

Dynamic Interval Temporal Logic

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November 17, 2017



Lecture 3: Event Structure

- Events as Structured Objects
- Event Types
 - States
 - Transitions
 - Point Verbs
 - Processes
- Events as Labeled Transition Systems
- Dynamic Event Models

Lab on detection of event types properties in corpora

Aktionsarten – conceptual categories of event types

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- (10) . a. The statue stands in the square.
b. The statue is standing in the square.

Structural vs. Phenomenal distinction – Goldsmith and Woisetschlager (1979)

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As seen with the English progressive marking before, states are not always permanent. Other languages also mark these differences (but not always for the same concepts).

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- Spanish – *ser* vs. *estar*

- (12) a. Soy enfermo (I am a sickly person)
b. Estoy enfermo (if I have a cold)

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Distinguishing Processes from Transitions

- Activities: Atelic i.e. have no natural endpoint or goal (e.g. *I'm running in the park*) Compatible with a durative adverbial (e.g. *for*) that profiles the amount of time the activity takes.

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- Accomplishments: Telic i.e. have a natural endpoint or goal (e.g. *I'm running a mile*) Compatible with a container adverbial (e.g. *in*) that profiles the amount of time taken to reach the desired goal.

Typological Effects

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(21) Jeg reser till Frankrike *på* två månader.

I('m) going to France for two months.

(22) Jeg reste i Frankrike *i* två månader.

I traveled in France for two months.

Achievements and points

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- (24) a. John shattered the window.
b. ! John shatters/is shattering the window.
c. The canals froze.
d. Mary found her keys.
e. *Mary is finding her keys.
f. John reached the top.

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b. The light flashed.
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- (27) a. Bill coughed.
b. The light flashed.
c. Bill is coughing.
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(c) and (d) have an iterative interpretation. Compare with the gradual achievements *John is reaching the top* or *The canals are freezing*.

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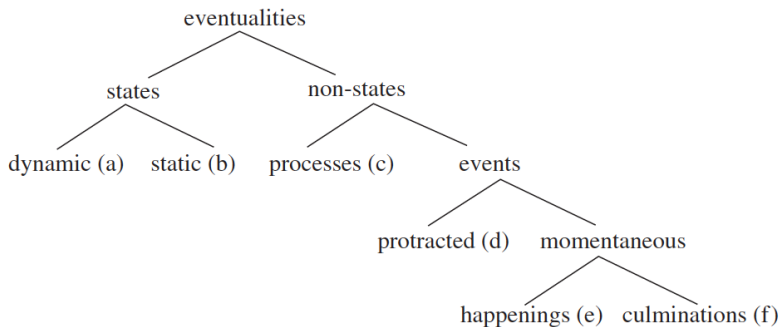
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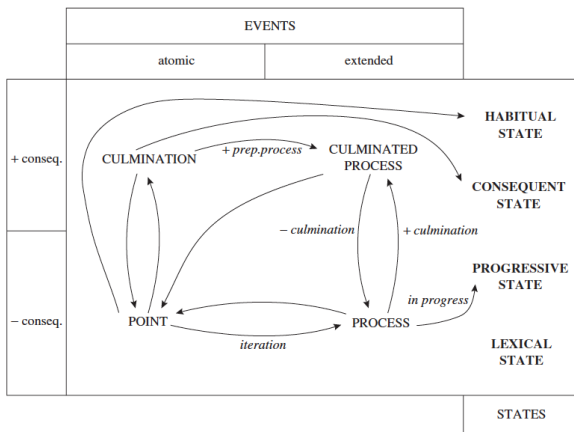
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- **POINT**: John knocked on the door (for 2 minutes).

Bach Eventuality Typology (Bach, 1986)



Event Transition Graph (Moens and Steedman 1988)



Incremental Theme Verbs

- Certain NP's **measure out the event**. They are direct objects consumed or created in increments over time (cf. *eat an apple* vs. *push a chart*) (Tenny 1994).

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- In *Mary drank a glass of wine* “every part of the glass of wine being drunk corresponds to a part of the drinking event” (Krifka 1992)
- “Incremental themes are arguments that are completely processed only upon termination of the event, i.e., at its end point” (Dowty 1991).

Degree Achievements

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- For example *cool*, *age*, *lengthen*, *shorten*; *descend*.
- *Let the soup cool for 10 minutes.*
- *I went on working until the soup cooled.*

Points

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- **Semelfactives** (Smith 1990, Rothstein 2004).
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- Points admit **iterative** readings under **coercive contexts** (Moens and Steedman 1988).

Aspectual Composition

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Aspectual Coercion

- “A person *leads* somebody somewhere” (PROCESS) vs. “A road *leads* somewhere” (STATE)

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- “A person *leads* somebody somewhere” (PROCESS) vs. “A road *leads* somewhere” (STATE)
- “An object *falls* to the ground” (TRANSITION) vs. “A case *falls* into a certain category” (STATE)

Subatomic Event Structure

Pustejovsky (1991)

(28) a. $\text{EVENT} \rightarrow \text{STATE} \mid \text{PROCESS} \mid \text{TRANSITION}$

Subatomic Event Structure

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- (29) a. $\text{EVENT} \rightarrow \text{STATE} \mid \text{PROCESS} \mid \text{TRANSITION}$
b. $\text{STATE:} \rightarrow e$

Subatomic Event Structure

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- (30) a. $\text{EVENT} \rightarrow \text{STATE} \mid \text{PROCESS} \mid \text{TRANSITION}$
b. $\text{STATE:} \rightarrow e$
c. $\text{PROCESS:} \rightarrow e_1 \dots e_n$

Subatomic Event Structure

Pustejovsky (1991)

- (31) a. $\text{EVENT} \rightarrow \text{STATE} \mid \text{PROCESS} \mid \text{TRANSITION}$
 b. $\text{STATE:} \rightarrow e$
 c. $\text{PROCESS:} \rightarrow e_1 \dots e_n$
 d. $\text{TRANSITION}_{ach}: \rightarrow \text{STATE STATE}$

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- (32) a. $\text{EVENT} \rightarrow \text{STATE} \mid \text{PROCESS} \mid \text{TRANSITION}$
 b. $\text{STATE:} \rightarrow e$
 c. $\text{PROCESS:} \rightarrow e_1 \dots e_n$
 d. $\text{TRANSITION}_{ach}: \rightarrow \text{STATE STATE}$
 e. $\text{TRANSITION}_{acc}: \rightarrow \text{PROCESS STATE}$

Qualia Structure for Causative

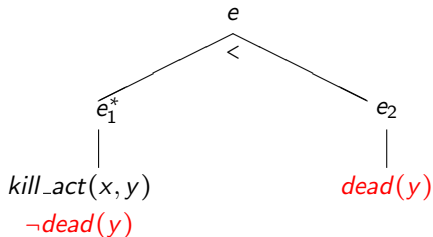
Pustejovsky (1995)

$$\left[\begin{array}{l} \text{kill} \\ \text{EVENTSTR} = \left[\begin{array}{l} E_1 = \mathbf{e_1:process} \\ E_2 = \mathbf{e_2:state} \\ \text{RESTR} = <_{\infty} \\ \text{HEAD} = \mathbf{e_1} \end{array} \right] \\ \text{ARGSTR} = \left[\begin{array}{l} \text{ARG1} = \boxed{1} \left[\begin{array}{l} \mathbf{ind} \\ \text{FORMAL} = \mathbf{physobj} \end{array} \right] \\ \text{ARG2} = \boxed{2} \left[\begin{array}{l} \mathbf{animate_ind} \\ \text{FORMAL} = \mathbf{physobj} \end{array} \right] \end{array} \right] \\ \text{QUALIA} = \left[\begin{array}{l} \mathbf{cause-lcp} \\ \text{FORMAL} = \mathbf{dead(e_2, \boxed{2})} \\ \text{AGENTIVE} = \mathbf{kill_act(e_1, \boxed{1}, \boxed{2})} \end{array} \right] \end{array} \right]$$

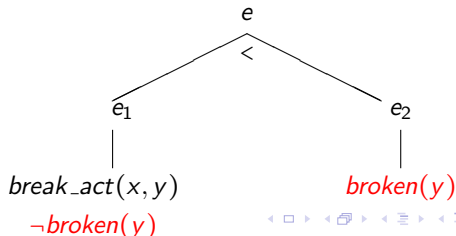
Opposition Structure

Pustejovsky (2000)

(33) kill



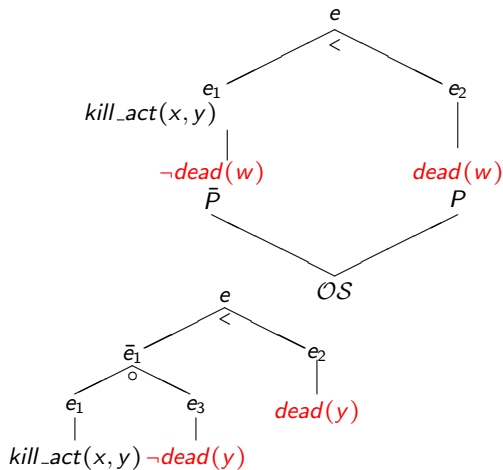
(34) break



Qualia Structure with Opposition Structure

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 \text{PRECOND} = \neg\text{dead}(\text{e}_0, \boxed{2})
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Opposition is Part of Event Structure



Dynamic Extensions to GL

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- **Dynamic Selection**: Encodes the way an argument participates in the event
- **Tracking change**: Models the dynamics of participant attributes

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Inherent Dynamic Aspect of Qualia Structure

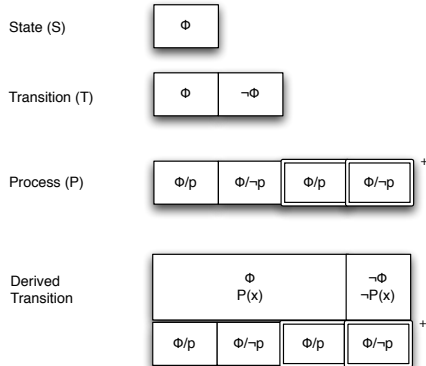
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$$\text{Verb}(\text{Arg}_1 \text{Arg}_2) \implies \lambda y \lambda x \boxed{P_1(x, y)}_A \boxed{P_2(y)}_F$$

Frame-based Event Structure



2nd Conference on CTF, Pustejovsky (2009)

Dynamic Event Structure

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- There may be many changes taking place within one atomic event, when viewed at the subatomic level.

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(Pustejovsky and Moszkowicz, 2011)

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 - $[\alpha]\phi$ (after every execution of α , ϕ is true);
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 - 5 Formulas can become programs, $\phi?$ (test to see if ϕ is true, and proceed if so).

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- (35) a. Mary was sick today.
b. My phone was expensive.
c. Sam lives in Boston.

Dynamic Event Structure

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We assume that a *state* is defined as a single frame structure (event), containing a proposition, where the frame is temporally indexed, i.e., $e^i \rightarrow \phi$ is interpreted as ϕ holding as true at time i . The frame-based representation from Pustejovsky and Moszkowicz (2011) can be given as follows:

Dynamic Event Structure

$$(37) \boxed{\phi}^i_e$$

Dynamic Event Structure

$$(40) \boxed{\phi}_e^i$$

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Semantic interpretations for these are:

$$(51) \text{ a. } [[\boxed{\phi}]]_{\mathbf{M},i} = 1 \text{ iff } V_{\mathbf{M},i}(\phi) = 1.$$

$$\text{ b. } [[\boxed{\phi}\boxed{\phi}]]_{\mathbf{M},\langle i,j \rangle} = 1 \text{ iff } V_{\mathbf{M},i}(\phi) = 1 \text{ and } V_{\mathbf{M},j}(\phi) = 1, \\ \text{ where } i < j.$$

Dynamic Event Structure

(52)

$$\begin{array}{c} e^i \\ | \\ \phi \end{array}$$

Dynamic Event Structure

(53)

$$\begin{array}{c} e^i \\ | \\ \phi \end{array}$$

Tree structure for event concatenation:

$$\begin{array}{c} e^i \\ | \\ \phi \end{array} + \begin{array}{c} e^j \\ | \\ \phi \end{array} = \begin{array}{c} e^{[i,j]} \\ | \\ \phi \end{array}$$

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- (60) a. S is the set of states;
b. Act is a set of actions;
c. $\rightarrow$ is a total transition relation: $\rightarrow \subseteq S \times Act \times S$.

(61) $(e_1, \alpha, e_2) \in \rightarrow$

cf. Fernando (2001, 2013)

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As a shorthand for

Labeled Transition System (LTS)

An action, α provides the labeling on an arrow, making it explicit what brings about a state-to-state transition.

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b. $e_1 \xrightarrow{\alpha} e_3$

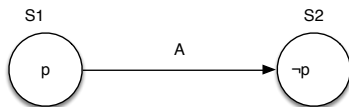
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If reference to the state content (rather than state name) is required for interpretation purposes, then as shorthand for:

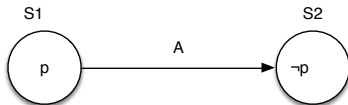
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$$(68) \quad \boxed{\phi}_{e_1} \xrightarrow{\alpha} \boxed{\neg\phi}_{e_2}$$



Temporal Labeled Transition System (TLTS)

With temporal indexing from a Linear Temporal Logic, we can define a Temporal Labeled Transition System (TLTS). For a state, e_1 , indexed at time i , we say $e_1 @ i$.

$(\{\phi\}_{e_1 @ i}, \alpha, \{\neg\phi\}_{e_2 @ i+1}) \in \rightarrow_{(i, i+1)}$, we use:

Temporal Labeled Transition System (TLTS)

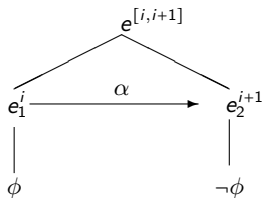
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$$(70) \quad \boxed{\phi}_{e_1}^i \xrightarrow{\alpha} \boxed{\neg\phi}_{e_2}^{i+1}$$

Dynamic Event Structure

(71)



Dynamic Event Structure

(72) Mary awoke from a long sleep.

Dynamic Event Structure

(74) Mary awoke from a long sleep.

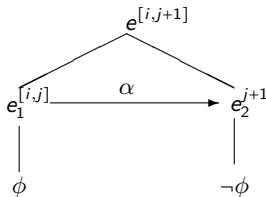
The state of being asleep has a duration, $[i, j]$, who's valuation is gated by the waking event at the “next state”, $j + 1$.

Dynamic Event Structure

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(77)



Simple First-order Transition

(78) $x := y$ (ν -transition)

" x assumes the value given to y in the next state."

$\langle \mathcal{M}, (i, i+1), (u, u[x/u(y)]) \rangle \models x := y$

iff $\langle \mathcal{M}, i, u \rangle \models s_1 \wedge \langle \mathcal{M}, i+1, u[x/u(y)] \rangle \models x = y$

Simple First-order Transition

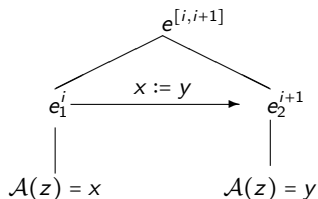
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(81)

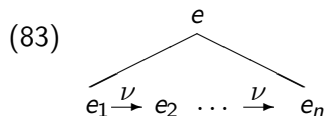


Processes

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arrive, leave, exit, land, take off

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Language Data

- **Manner construction languages**

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- **Path construction languages**

Path information is encoded in matrix verb, while adjuncts specify manner of motion

Modern Greek, Spanish, Japanese, Turkish, Hindi

Defining Motion (Talmy 1985)

(84) a. The *event* or situation involved in the change of location ;

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Defining Motion (Talmy 1985)

- (87) a. The *event* or situation involved in the change of location ;
b. The object (construed as a point or region) that is undergoing movement (the *figure*);
c. The region (or *path*) traversed through the motion;
d. A distinguished point or region of the path (the *ground*);

Defining Motion (Talmy 1985)

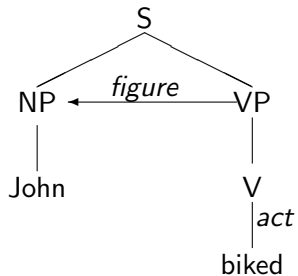
- (88) a. The *event* or situation involved in the change of location ;
b. The object (construed as a point or region) that is undergoing movement (the *figure*);
c. The region (or *path*) traversed through the motion;
d. A distinguished point or region of the path (the *ground*);
e. The *manner* in which the change of location is carried out;

Defining Motion (Talmy 1985)

- (89) a. The *event* or situation involved in the change of location ;
b. The object (construed as a point or region) that is undergoing movement (the *figure*);
c. The region (or *path*) traversed through the motion;
d. A distinguished point or region of the path (the *ground*);
e. The *manner* in which the change of location is carried out;
f. The *medium* through which the motion takes place.

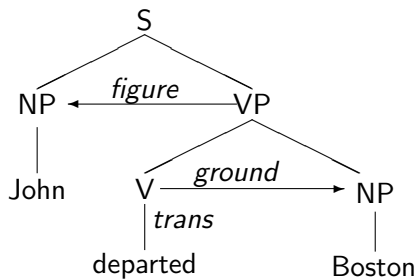
Manner Predicates

(90)



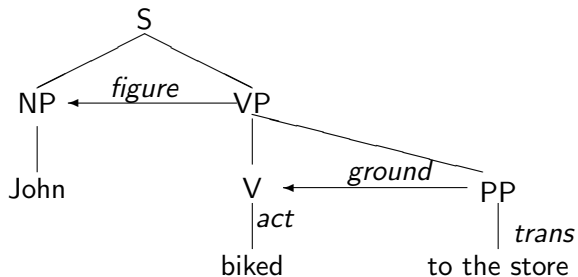
Path Predicates

(91)



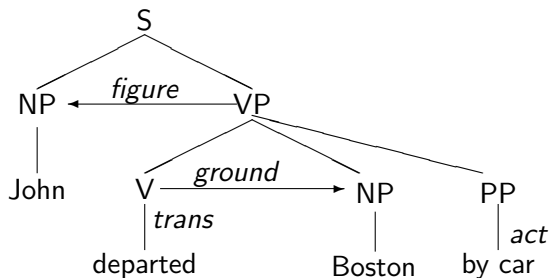
Manner with Path Adjunction

(92)



Path with Manner Adjunction

(93)



Path+manner Predicates (Talmy 2000) 1/2

(94) a. Isabel climbed for 15 minutes.

Path+manner Predicates (Talmy 2000) 1/2

- (96) a. Isabel climbed for 15 minutes.
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- (98) a. Isabel climbed for 15 minutes.
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Path+manner Predicates (Talmy 2000) 1/2

- (100) a. Isabel climbed for 15 minutes.
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- (101) a. There is an action (e) bringing about an iterated non-distinguished change of location;
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Path+manner Predicates (Talmy 2000) 1/2

- (102) a. Isabel climbed for 15 minutes.
b. Nicholas fell 100 meters.
- (103) a. There is an action (e) bringing about an iterated non-distinguished change of location;
b. The figure undergoes this non-distinguished change of location;
c. The figure creates (leaves) a path by virtue of the motion.

Path+manner Predicates (Talmy 2000) 1/2

- (104) a. Isabel climbed for 15 minutes.
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- (105) a. There is an action (e) bringing about an iterated non-distinguished change of location;
b. The figure undergoes this non-distinguished change of location;
c. The figure creates (leaves) a path by virtue of the motion.
d. The action (e) is performed in a certain manner.

Path+manner Predicates (Talmy 2000) 1/2

- (106) a. Isabel climbed for 15 minutes.
b. Nicholas fell 100 meters.
- (107) a. There is an action (e) bringing about an iterated non-distinguished change of location;
b. The figure undergoes this non-distinguished change of location;
c. The figure creates (leaves) a path by virtue of the motion.
d. The action (e) is performed in a certain manner.
e. The path is oriented in an identified or distinguished way.

Path+manner Predicates (Talmy 2000) 2/2

Unlike pure manner verbs, this class of predicates admits of two compositional constructions with adjuncts.

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John climbed to the summit.

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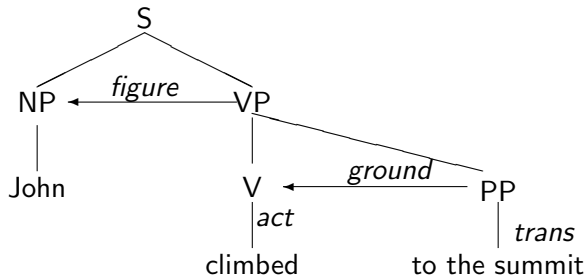
John climbed to the summit.

(113) **Manner of motion verb with path argument;**

John climbed the mountain.

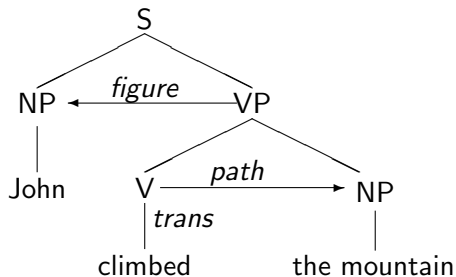
With Path Adjunct

(114)

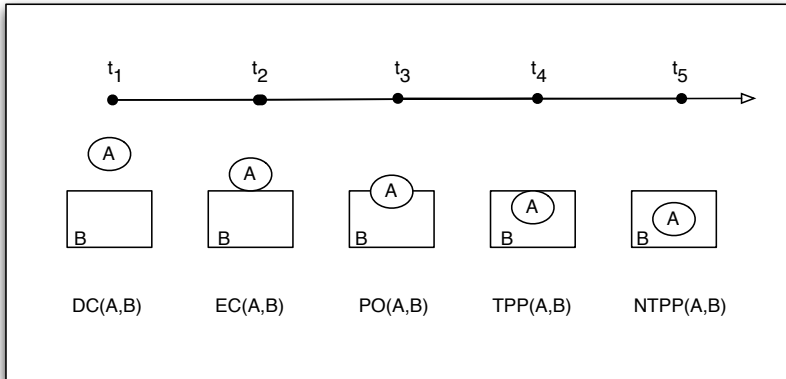


With Path Argument

(115)



Tracking Motion with RCC8: example of enter



Capturing Motion as Change in Spatial Relations

Dynamic Interval Temporal Logic

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Dynamic Interval Temporal Logic

- **Path** verbs designate a distinguished value in the change of location, from one state to another.
The change in value is **tested**.
- **Manner of motion** verbs iterate a change in location from state to state.
The value is **assigned** and reassigned.

Directed Motion

$$(116) \quad \boxed{loc(z) = x}_{e_1} \xrightarrow{\nu} \boxed{loc(z) = y}_{e_2}$$

$x \neq y?$


Directed Motion

$$(118) \quad \boxed{\overset{x \neq y?}{\curvearrowright} \text{loc}(z) = x}_{e_1} \xrightarrow{\nu} \boxed{\text{loc}(z) = y}_{e_2}$$

When this test references the ordinal values on a scale, $\mathcal{C}$, this becomes a *directed ν -transition* ($\vec{\nu}$), e.g., $x \leq y$, $x \geq y$.

Directed Motion

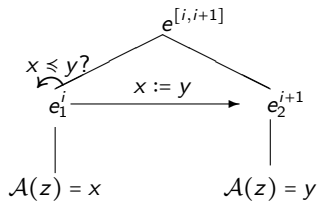
$$(120) \quad \boxed{\overset{x \neq y?}{\curvearrowright} \text{loc}(z) = x}_{e_1} \xrightarrow{\nu} \boxed{\text{loc}(z) = y}_{e_2}$$

When this test references the ordinal values on a scale, $\mathcal{C}$, this becomes a *directed ν -transition* ($\vec{\nu}$), e.g., $x \leq y$, $x \geq y$.

$$(121) \quad \vec{\nu} =_{df} \overset{\mathcal{C}^?}{\curvearrowright} e_i \xrightarrow{\nu} e_{i+1}$$

Directed Motion

(122)



Change and Directed Motion

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loc(x) := y; y := z

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- Path verbs introduce a pair of **tests**:

$\neg\phi? \dots \phi?$

Change and the Trail it Leaves

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- For motion, this trail is the created object of the path p which the mover travels on;
- For creation predicates, this trail is the created object brought about by order-preserving transformations as executed in the directed process above.

Motion Leaving a Trail

(123) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

Motion Leaving a Trail

(124) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

- b. Name this value b (this will be the beginning of the movement);

$b := y$

Motion Leaving a Trail

(125) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

- b. Name this value b (this will be the beginning of the movement);

$b := y$

- c. Initiate a path p that is a list, starting at b ;

$p := (b)$

Motion Leaving a Trail

(126) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

- b. Name this value b (this will be the beginning of the movement);

$b := y$

- c. Initiate a path p that is a list, starting at b ;

$p := (b)$

- d. Then, reassign the value of y to z , where $y \neq z$

$y := z, y \neq z$

Motion Leaving a Trail

(127) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

- b. Name this value b (this will be the beginning of the movement);

$b := y$

- c. Initiate a path p that is a list, starting at b ;

$p := (b)$

- d. Then, reassign the value of y to z , where $y \neq z$

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- e. Add the reassigned value of y to path p ;

Motion Leaving a Trail

(128) MOTION LEAVING A TRAIL:

- a. Assign a value, y , to the location of the moving object, x .

$loc(x) := y$

- b. Name this value b (this will be the beginning of the movement);

$b := y$

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- d. Then, reassign the value of y to z , where $y \neq z$

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- e. Add the reassigned value of y to path p ;

$p := (p, z)$

- f. Kleene iterate steps (d) and (e).

Quantifying the Resulting Trail

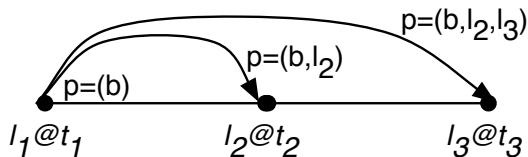


Figure: Directed Motion leaving a Trail

Quantifying the Resulting Trail

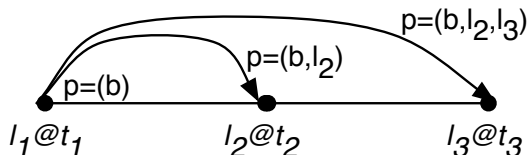


Figure: Directed Motion leaving a Trail

(130) a. The ball rolled 20 feet.

$$\exists p \exists x [[roll(x, p) \wedge ball(x) \wedge length(p) = [20, foot]]]$$

Quantifying the Resulting Trail

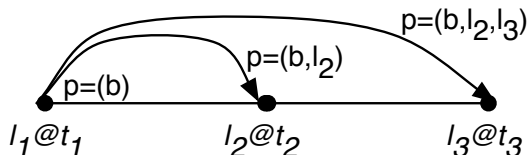


Figure: Directed Motion leaving a Trail

(131) a. The ball rolled 20 feet.

$$\exists p \exists x [[roll(x, p) \wedge ball(x) \wedge length(p) = [20, foot]]]$$

b. John biked for 5 miles.

$$\exists p [[bike(j, p) \wedge length(p) = [5, mile]]]$$

Generalizing the Path Metaphor

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- We analyze creation predicates as predicates referencing two types of scales.

Type of Creation Verbs

(132) a. John wrote a letter.

Type of Creation Verbs

- (134) a. John wrote a letter.
b. Sophie wrote for hours.

Type of Creation Verbs

- (136) a. John wrote a letter.
b. Sophie wrote for hours.
c. Sophie wrote for an hour.
- (137) a. John built a wooden bookcase.
b. *John built for weeks.

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- For example, Rappaport Hovav 2008, Kennedy 2009 claim that “the scale which occurs with incremental theme verbs (extent scale) is **not directly encoded** in the verb, but rather provided by the referent of the direct object”.
- This has lead them to the assumption that when nominal reference plays a role in measuring the change, V is not associated with a scale (denoting a non-scalar change).

Challenge for Scalar Models

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- What is the role of nominal reference in aspectual composition?

How Language Encodes Scalar Information

Pustejovsky and Jezek 2012

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- Verbs may reference multiple scales.

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- **Interval scales:** have equal distances between scale units and permit statements to be made about those units as compared to other units; there is no zero. Interval scales permit a statement of “more than” or “less than” but not of “how many times more.”
- **Ratio scales:** have equal distances between scale units as well as a zero value. Most measures encountered in daily discourse are based on a ratio scale.

Generalizing the Path Metaphor to Creation Predicates

Pustejovsky and Jezek 2012

- Use multiple scalar domains and the “change as program” metaphor proposed in Dynamic Interval Temporal Logic (DITL, Pustejovsky 2011, Pustejovsky & Moszkowicz 2011).

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- If the program is “change by assignment”, Result refers to the record or trail of the change (e.g., the **path** of a **walking**, the **stuff written** in **writing**, etc.).

Scale shifting

Pustejovsky and Jezek 2012

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- Scale Shifting is mapping from one scalar domain to another scalar domain.

ordinal $\Rightarrow$ nominal

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- Adjuncts: *for/in* adverbials, degree modifiers, resultative phrases, etc.
- Arguments (selected vs. non-selected, semantic typing, quantification).

Generalizing the Path Metaphor to Creation Predicates

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Accomplishments are Lexically Encoded Tests.

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John **built** a house.

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Generalizing the Path Metaphor to Creation Predicates

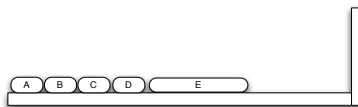
Pustejovsky and Jezek 2012

Accomplishments are Lexically Encoded Tests.

John **built** a house.

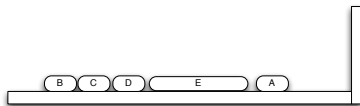
- Test-predicates for creation verbs
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- $\lambda \vec{z} \lambda y \lambda x [\textit{build}(x, \vec{z}, y)]$
- An **ordinal scale** drives the incremental creation forward
- A **nominal scale** acts as a test for completion (telicity)

Incremental Theme and Parallel Scales



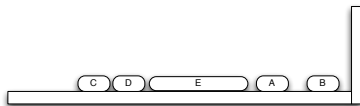
- Mary is building a table.
- Change is measured over an **ordinal scale**.
- Trail, τ is null.

Incremental Theme and Parallel Scales



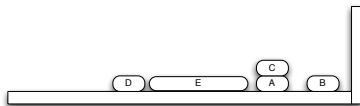
- Mary is building a table.
- Change is measured over an **ordinal scale**.
- Trail, $\tau = [A]$.

Incremental Theme and Parallel Scales



- Mary is building a table.
- Change is measured over an **ordinal scale**.
- Trail, $\tau = [A, B]$

Incremental Theme and Parallel Scales



- Mary is building a table.
- Change is measured over an **ordinal scale**.
- Trail, $\tau = [A, B, C]$

Incremental Theme and Parallel Scales



- Mary is building a table.
- Change is measured over an **ordinal scale**.
- Trail, $\tau = [A, B, C, D]$

Incremental Theme and Parallel Scales



- Mary built a table.
- Change is measured over a **nominal scale**.
- Trail, $\tau = [A, B, C, D, E]$; $table(\tau)$.

Accomplishments

- (138) a. John built a table.
 b. Mary walked to the store.

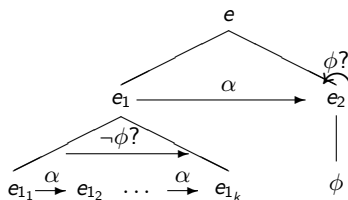
$build(x, z, y)$	$build(x, z, y)^+$	$build(x, z, y), y = v$
$\neg table(v)$		$table(v)$

 (i, j)

Table: Accomplishment: parallel tracks of changes

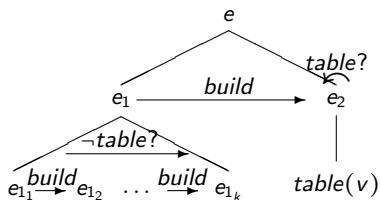
Dynamic Event Structure

(139)



Parallel Scales define an Accomplishment

(140)



Lab on identification of event type properties in corpora

- Choose three target verbs. State your hypothesis regarding the event type associated with the verbs wrt to the extended in time vs instantaneous dimension.
- Count the co-occurrences of the verbs in the rows of the matrix with the expressions in the columns in the BNC using the SkE.
- You can use the context search - setting the window, or refine your search with CQL or Word Sketches.

Lab on detection of event type properties in corpora

- For the "for x time" expressions, you can use the following regular expression:
`[lemma = "for"][]{0,1}[lemma = "instant|second|minute|hour|day|week|month|year"]`
- Fill the cooccurrence counts in last column of the matrix and rank the verbs accordingly.
- Select 1 concordance for each verb which constitutes an example of event-type shiftings in context.
- Summarize your results.

Lab on detection of event type properties in corpora

Co-occurrence matrixes detecting extended vs. instantaneous events

	suddenly	still	for x time	finishV	total occ
happen					
occur					
breathe					
appear					
die					
sleep					
walk					
run					
laugh					
wake up					
fall					
develop					
watch					
freeze					

Ongoing work E. Jezek, M. Sadrzadeh and E. Ponti (unpublished).